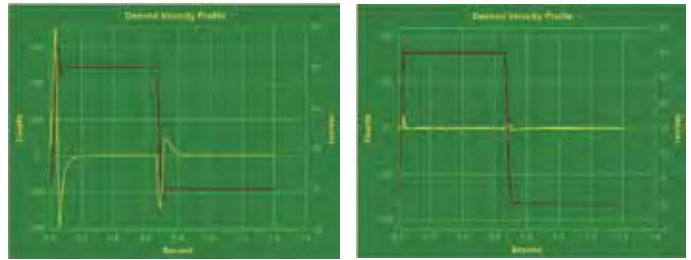


DC t
/ 6 i (Q

■ TM 2 Ɔ ƚ ƚ ƚ

/pServoSuite Ɔ G : ƚ F* ƚ ƚ ƚ - % ƚ
 ƚ b ƚ ƚ , ƚ TM 2 ƚ ƚ ƚ ƚ ƚ ƚ ,
 Q ƚ ƚ ƚ ƚ ƚ ^ , / ƚ ƚ ƚ ƚ ƚ ƚ y +
 » ƚ ƚ ƚ , ƚ ƚ ƚ » ƚ ƚ - .

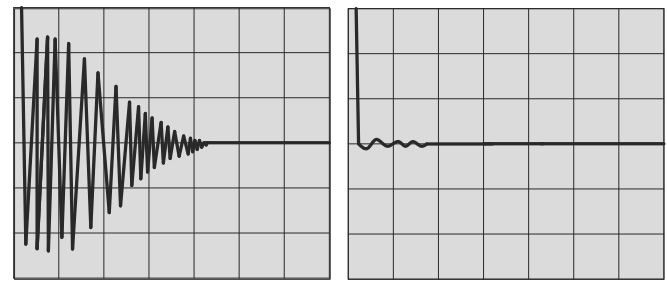
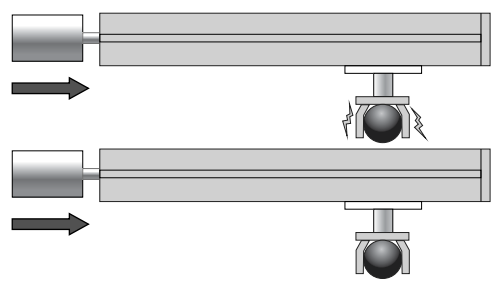
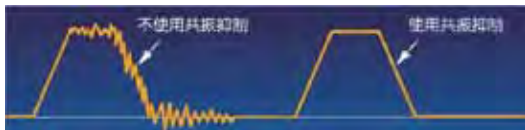


: gy+oà Ɔ ƚ ƚ ƚ ' , : gy+oà Ɔ ƚ ƚ ƚ P ,
 w ƚ " ƚ n ƚ ƚ f ƚ ƚ Ö ƚ ƚ , w ƚ " ƚ n ƚ ƚ f ƚ U

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DC i (Q Ü ƚ , f ƚ ^ É d Ü , f " ý H R Ü ƚ Ö % ƚ k
 Ü , f ƚ ^ ! ~ ƚ 7 Ü g (Notch Filters) ,
 % ƚ ƚ (ƚ • y + : Ü F] ƚ % ± ƚ 4 F
 Ü ƚ ƚ .

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 ý H R Ü ƚ ^ : / p » ƚ f g ! ~ ý H ƚ ƚ ƚ ž
 Ö ƚ Q ý H ± ƚ , / ƚ % ƚ R 4 Q Ü ƚ .



Ɔ ý H R Ü ƚ ^ ' h ý H R Ü ƚ ^

■ • K ƚ • M

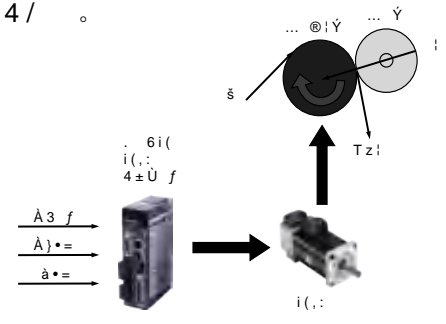
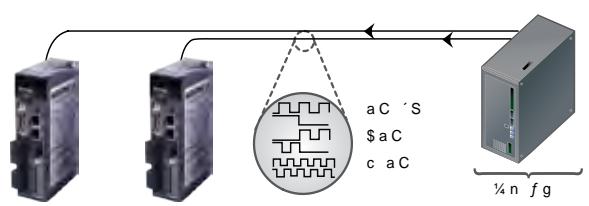
% % • K V . ƚ • M ƚ y _ STO (Safe Torque Off) ƚ ^ . (I S ƚ b | :] • b)
 ƚ ƚ ƚ } b (Safe Torque Off) ƚ ƚ ƚ ƚ ƚ ƚ ƚ ƚ . FSTO ƚ ^ ƚ z ƚ , ƚ ƚ g ƚ ƚ ƚ , x W N & , A f
 ! ƚ ƚ ƚ g . % ƚ ƚ - , / ƚ ƚ b , : 1 z , ƚ ƚ g * c • ^ ƚ ƚ - . ƚ ƚ ƚ ± ƚ ƚ g ä , ,] I , Ö N g ,
 : TM ƚ ƚ ƚ E ƚ ƚ ƚ • ƚ ƚ y + ƚ ƚ .
 : UL61800-5-1, UL61800-5-2 b | Ö

■ Ɔ Ü Ü a C n ƚ 4 /

, ƚ ƚ S & a C , CW/CCW \$ a C , A/B c a C ä
 集电极开路脉冲输入: 500KHz, 5-24VDC
 线性差分脉冲输入: 2MHz, 5VDC

■ 4 ± Ü ä f

ƚ x 4 ± Ü ä , ƚ ƚ 4 ± Ü n ƚ , 4 ± Ü 3 , " 4
 ± Ü ! } 4 / .



■ . μ %, @ , m ... , ý

δ @ g t . μ %, @ , m ... , ý , # 7 : m ... 20W .

■ . μ Æ PLC — ± % Q f - © ^

Q - ý æ x % \$ `™ SCL È = ò ¨ ç ¼ ¶ Ó ³ ð ; , p X
 ý SCL • = • x , t x Y x \$ À Ú ñ SCL È = . - ý :
 > ³ Ú ™ ð @ g c Ú > - Ú ñ g Ö , ð @ Æ ¼ n : : x`
 à - ý . Q - ý Ý Q y ! ~ ý 3 & 2 - - A 7
 © ^ . : > 7 7 ð Æ ¼ n : ' _ PLC • f g f - 1 z .

Line	Label	Cmd	Param1	Param2	Comment
1		DI	1800		点动占时点动时间为1800个脉冲
2		RX	2	-1	自定义寄存器-地址为"-1"
3	Label2	WT	0.5		等待0.5s
4		TI	3L		判断输入是否否为on
5		QI	T	#Label1	输入为ON, 激活前 Label1
6		VE	5		否则设定速度为5m/s
7		TI	2L		判断输入是否否为on
8		QI	T	#Label1	输入为ON+ 激活前 Label1
9		VE	18		否则设定速度为18m/s
10		TI	3L		判断输入是否否为on
11		QI	T	#Label1	输入为ON+ 激活前 Label1
12		VE	20		否则设定速度为20m/s
13		QI	#Label2		循环判断 #1, #2, #3输入状态
14	Label1	PL			开断点动点动时间
15	R*	D	2		点动点动寄存器=每数据寄存器-地址
16	R#	D	D		寄存器地址=寄存器-地址+寄存器地址寄存器D
17	PL				再开断执行点动时间
18	R*	D	2		点动点动寄存器=每数据寄存器-地址
19	R#	D	D		寄存器地址=寄存器-地址+寄存器地址寄存器D
20	QS	#Label2			检测Label2, 开始重新循环

特性

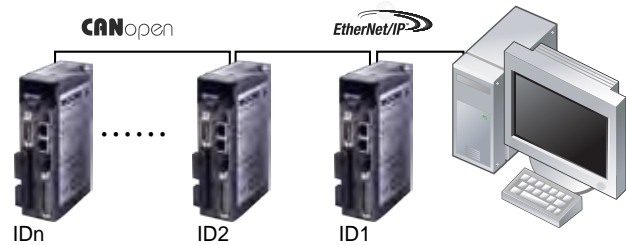
- @ f È = (' _ A • A 0 * @ , O * @ , • A •)
- 2 1 « * 0 È =
- M G { ± È = (' _ 0 % ä Ö ± È = , Š Ö È = •)
- æ ð Ú g a È = (' _ a , R , ñ , • Ä , J • È =)
- 0 % / O * 0 (' _ 0 % ä { ± , ð @ g ä b f • È =)
- Q - ý > ä à È = (' _ o , » x)

■ ³ 2 f

1 È - @ ð £ K Ú ™ a 2 ð £ ³ 2 / l x . DC t i (Q : > , Æ ð RS-485 Modbus ³ 2 , ð CAN
 CANopen ³ 2 , ð > 9 © EtherNet/IP , > " - ý æ eSCL è k , ! ~ ý x £ ³ 2 Ü È .



	RS-485 ³ 2	CAN ³ 2	> 9 © ³ 2
è k • M	Modbus/RTU	CiA301, CiA402	EtherNET/IP eSCL
³ 2 /	CN6 ÈCN7 (RJ45)	CN6 ÈCN7 (RJ45)	CN6 ÈCN7 (RJ45)
/ 13	9600bps 19200bps 38400bps 57600bps 115200bps	12.5Kbps 25kbps 50Kbps 125Kbps 250Kbps 500Kbps 800Kbps 1Mbps	10/100Mbps
f 4 /	n μ 4 / 3 4 / ! } 4 /	n μ 4 / 3 4 / ! } 4 / • A	n μ 4 / 3 4 / ! } 4 /



■ x ä ä b /

- 2 x • MEIA-422 3 3 ç k ¶ A ä /
- 4 x 5-24VDC 3 3 ä / , ... a C Ý 3 ù 500KHz , Û œ Û Û © ^
- 8 x 5-24VDC / x ä /
- 2 x 4 ± Û ä /
- 6 x # 730VDC 30mA / x ä b /

■ 'l qzf[, #] » Ž Ā G

- μ4s-Ū qzf[
- /p qzf[ø Fð4 œ yÿÀ%›
- LED:<Ð" ð@g Ð Ā-



Servo Suite » Ž Ā G

- #] xYœf
- ði yμqz
- ,Æ ð@g œyÿ" μ ¼ [½ Ñ
- ði Ūx ™ 2-@žÿ©^
- .μç g"<©^ , K @» Ž"
- ,Æ SCLm 4 È= » Ž Ā³ Ū
- 6 F ™ 2 P^-©^



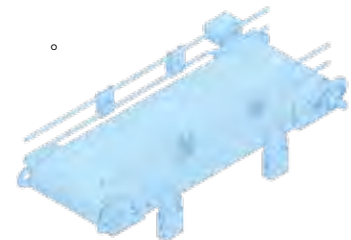
■ nμê©^

- É d/2 @ , '† @
- /2 @/pœ Ū Ū ä ¶ A ĩ N7K , \$, N&2 ù 63 Ó.\$ nμA
(0*JçO* @)
- '† @,Æ 48 Ó•kA
- :-•yÿ† Ó nμA 3 "aR3 , @ a ð Ī
- Ā 1¼ n:& aC : 2A f , ë 4¼ n:aC ä b 4° •x
- ð ¼ n:f-
x£K : /247 , À; , k '•



■ 2•3 f

- 3 4/½/pä ¶ A ĩ N7K , \$,873 Ö ¶ 7zÝ,: À 3 È=
- •xœ Ū Ū ä ¶ A , ¼ n:Ā 14± Ū ä b 4°
- :>/p Ā G J qzf[-•½ † 873
- 13 • a3 , R3 ":-•yÿ
x£K : i Ū , [Ū•



■ lð

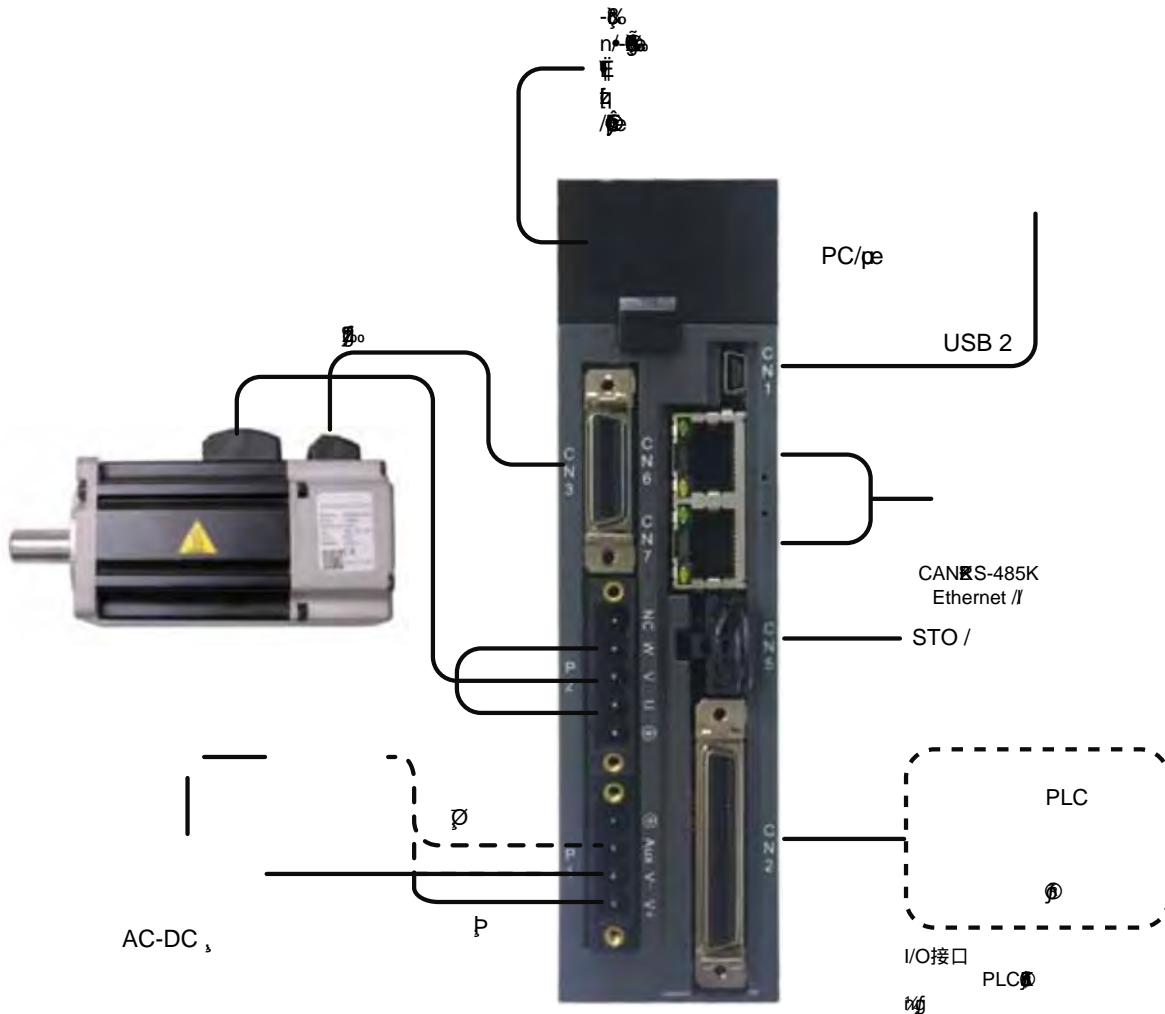
™ Ñ ð E J ç [@ F] * Ð P , lð ĩ N œ ,
> .³ ĩ N¹ E ½ Q ^ 46 ÿ : d 1 z .
x£K : : Ū c ¥ , Æ / Ñ , [Ū •



■ aC b (ã • „ (© ^)

nμ 4/½ , • x ¶ Ó 0% ¶ A z Ý a C b © ^ N &
¶ A . F ž ¶ A % œ Ð , : 1 ` â b ò " 0%
aC ä b .
x£K : É : Ū •





DC - □ □ □ 5 □ ***

DC i (ō®g

,6 < A],6 (RMS)	Ž 0,6 (RMS)
6D0	6.0A	18.0A
10D	10.0A	20.0A

ŷ f < A

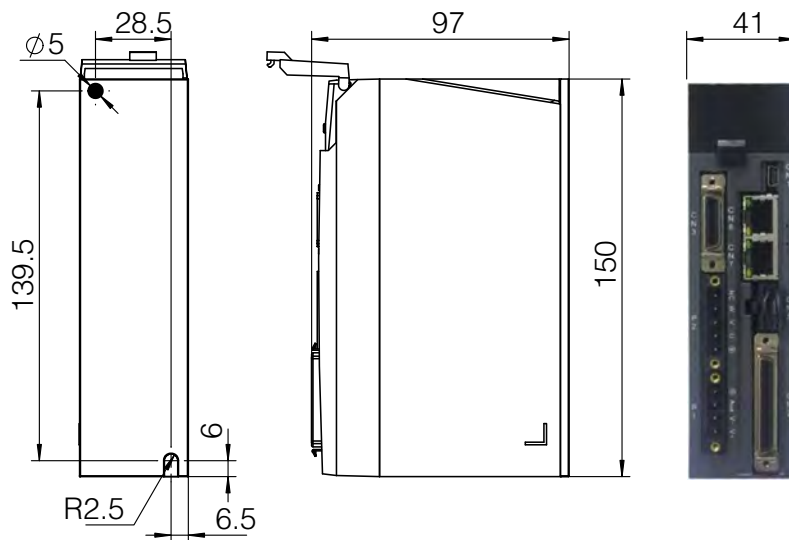
/I < A	μ ' /	ò 4 Ě	/I ' /
S	USB Mini-B	ò 4 Ě	---
Q		Q f - Ě	RS-232
R		Q f - Ě (d Modbus/RTU)	RS-485
C		CANopen Ě	CAN ³ 2
D		eSCL Ě	Ethernet
IP		E herNet/IP Ě	Ethernet

, < A	ä ,
5	20-60VDC

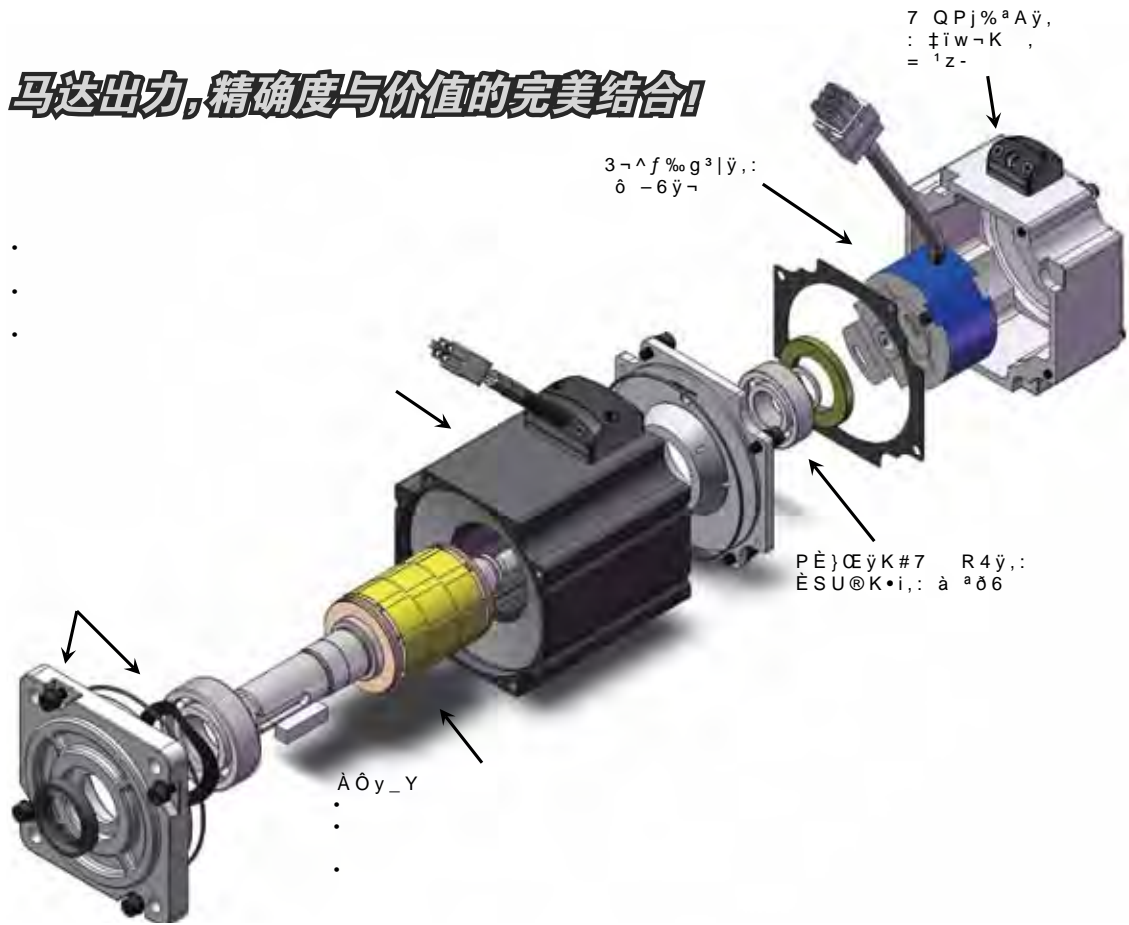
■ $\delta \otimes g : a$

0 4 : a	ä , ,	DC-6D0	$P \cdot x , ,$	20-60VDC	
		DC-10D	$f \cdot x , ,$	10-60VDC	
	• x	•	• x • : 0°C to 50°C (_ f • S p 40°C, $\bar{\mu} / ^2 \acute{a}] \acute{E}]$) Ú ñ • : -20°C to 65°C		
		z	Ú ñ " • x : 10 to 85%RH		
		Q ©	Q © 1000m > ½		
		Ü ®	5.88m/s ² > ½ , 10 to 60Hz ([™] Ü A * ç : Æ] • x)		
	f ' /		IGBT PWM c 9 f		
	f % g % ß		2500 2 Û 4 2 / f % g		
	I/O	œ Û ¶ A	ä	8 x ø % / x ä , : / p œ µ © ^ , 5-24VDC, 20mA 2 x ø % 3 3 ä , : / p œ µ © ^ , 5-24VDC, 20mA	
			ä b	6 x ø % / x ä b , : / p œ µ © ^ , # 7 30VDC, 20mA	
		4 ± Û ¶ A	ä	2 x 4 ± Û ä , k ñ 12bit	
		a C ¶ A	ä	2 x 500KHz 6 , \ ' x 3 3 ä , : µ Ý / x œ Û ä ¶ A 2 x 2MHz 2 - ð ® ç k ¶ A ä	
	ä b		3 x f % g % ß ä b , 2 - ç k ¶ A , \$ Ö A \ B 0 10000 Ó a C ± " , Z 0 1 Ó a C ± "		
	/ I	USB Mini-B		x PC : à Æ G » Ž	
		RS232		x RS-232 / I	
		RS485		x RS-485 / I " Modbus/RTU	
		CAN bus		CANopen ³ 2 / I	
		Ethernet		EtherNET/IP, eSCL	
q z f [4 Ó q z Ê (MODE, UP, DOWN, SET) , 5 n LED i ç			
2 v , ý		. µ 2 v , ý 20W			
® - † »		. µ			
f 4 /		1. n µ 4 / 2. 4 ± Û 3 4 / 3. 4 ± Û n µ 4 / 4. n µ ê 5. 2 • 3 4 / 6. . % Å } 4 / 7. . % 3 4 / 8. n µ ê			
f ä ¶ A		1. Servo-ON ä 2. • \ Ç ä 3. CW/CCW n 4. a C & ' S J CW/CCW a C ä 5. l ð 6. ¹ z 4 / l ð 7. a C b ä 8. / x ä			
f ä b ¶ A		1. • \ ä b 2. Servo-Ready ä b 3. , : f ® g f ä b 4. 3 • ù ä b ; 5. Å } • ù ä b 6. n µ • ù ä b 7. Tach Out 8. / x ä b			
b		RoHS, EN 61800-3, EN 61800-5-1			

■ $\delta \otimes g : \acute{U} F (i n : mm)$



马达出力, 精确度与价值的完美结合!



SM0602FE4-KCD-NNV**

SM t		† » < %g		ÿf < A	
: F)		N: ç Û f ® g		b È " 22 Û È	
04-□40mm		B: Û 24VDC f ® g		KCD: • M f . b È , c / È § g ,6A > ½ H7	
06-□60mm				KCF: • M f . b È , c / È § g ,10A > ¼ H7	
08-□80mm				f %g Û È	
: Á				E4: 2500 2 Û / f %g	
□40 □60 □80		H7 :ª (DC)			
01	60W 200W 300W	E	80V		
02	100W 400W 550W	F	60V		
		G	48V		
		H	36V		

■ , :: a

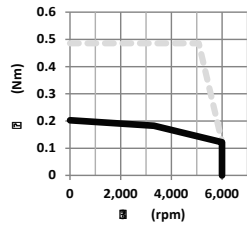
□ o, , :

2500 2 Û / , :		SM0401HE4-KCD-NNV	SM0402FE4-KCD-NNV	SM0601GE4--KCF-NNV	SM0801GE4-KCF-NNV	SM0602FE4-KCF-NNV
õ@g ä ,		36	60	48	48	60
ÿ ä b@	watts	60	100	200	300	400
ÿ Å 3	rpm	3000	3000	3000	3000	3000
# 7 Å 3	rpm	6000	6000	6000	6000	6000
ÿ Å }	Nm	0.19	0.32	0.64	0.95	1.27
Ž Ø Å }	Nm	0.48	0.91	1.9	2.3	3.6
ÿ , 6	A (rms)	5.7	5.2	10	10	10
Ž Ø , 6	A (rms)	14.3	15.6	30	25	30
% , , á œ	V (rms) / K rpm	2.1	3.8	4.1	6.2	7.4
Å } œ	Nm / A (rms)	0.035	0.061	0.065	0.096	0.123
H 7 , ý (Line-Line)	Ohm@25°C	0.36	0.48	0.192	0.188	0.25
H 7 , ‡ (Line-Line)	mH (typ.)	0.39	0.58	0.56	0.85	0.84
Å @ Û - ÿ Û f@g	kg m^2	0.0232 × 10 ⁻⁴	0.0428 × 10 ⁻⁴	0.165 × 10 ⁻⁴	0.45 × 10 ⁻⁴	0.272 × 10 ⁻⁴
Å @ Û - Û f@g	kg m^2	0.0298 × 10 ⁻⁴	0.0494 × 10 ⁻⁴	0.22 × 10 ⁻⁴	0.53 × 10 ⁻⁴	0.326 × 10 ⁻⁴
È S Ñ	N (max.)	50	50	70	90	70
^ S Ñ (È 3 j)	N (max.)	50	60	200	200	240
x Û - ÿ Û f@g	kg	0.4	0.55	1.1	1.7	1.4
x Û - Û f@g	kg	0.65	0.8	1.6	2.5	1.9

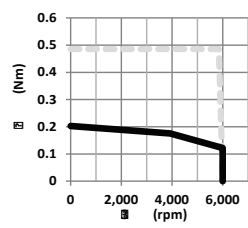
□ 3, , :

2500 2 Û / , :		SM0401EE4-KCD-NNV	SM0601EE4-KCD-NNV	SM0802EE4-KCF-NNV
õ@g ä ,		80	80	80
ÿ ä b@	watts	60	200	550
ÿ Å 3	rpm	3000	3000	3000
# 7 Å 3	rpm	6000	6000	5500
ÿ Å }	Nm	0.19	0.64	1.8
Ž Ø Å }	Nm	0.48	1.9	4.6
ÿ , 6	A (rms)	2.6	5.2	10
Ž Ø , 6	A (rms)	6.5	15.6	28
% , , á œ	V (rms) / K rpm	4.6	7.9	11.2
Å } œ	Nm / A (rms)	0.077	0.125	0.176
H 7 , ý (Line-Line)	Ohm@25°C	1.67	0.67	0.22
H 7 , ‡ (Line-Line)	mH (typ.)	1.88	2	1.25
Å @ Û - ÿ Û f@g	kg m^2	0.0232 × 10 ⁻⁴	0.165 × 10 ⁻⁴	0.63 × 10 ⁻⁴
Å @ Û - Û f@g	kg m^2	0.0298 × 10 ⁻⁴	0.22 × 10 ⁻⁴	0.71 × 10 ⁻⁴
È S Ñ	N (max.)	50	70	90
^ S Ñ (È 3 j)	N (max.)	50	200	240
x Û - ÿ Û f@g	kg	0.4	1.1	2.2
x Û - Û f@g	kg	0.65	1.6	3.0

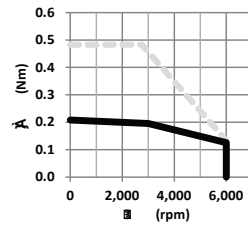
SM0401EE4(60 Watts) -2.6Amps
DC Bus--48VDC



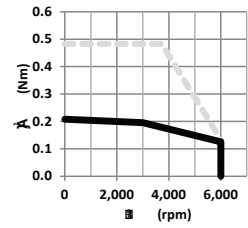
SM0401EE4(60 Watts) -2.6Amps
DC Bus--60VDC



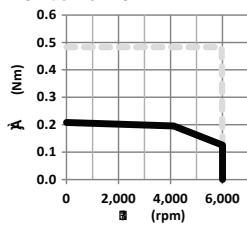
SM0401HE4(60 Watts) -5.7 Amps
DC Bus--24VDC



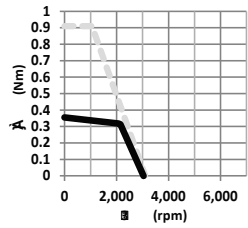
SM0401HE4(60 Watts) - 5.7 Amps
DC Bus--36VDC



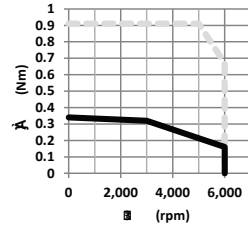
SM0401HE4(60 Watts) - 5.7 Amp
DC Bus--48VDC



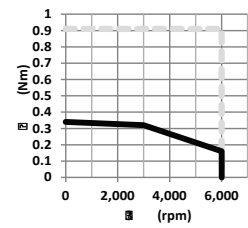
SM0402FE4(100 Watts) -5.2Amps
DC Bus--24VDC



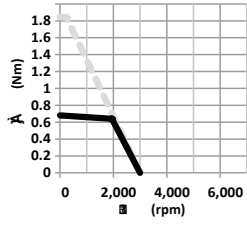
SM0402FE4(100 Watts) -5.2Amps
DC Bus--48VDC



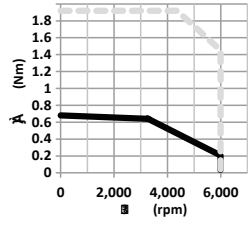
SM0402FE4(100 Watts) -5.2Amps
DC Bus--60VDC



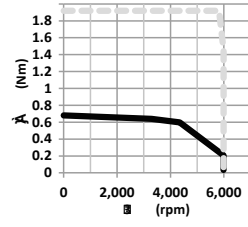
SM0601GE4(200 Watts) -10Amps
DC Bus--24VDC



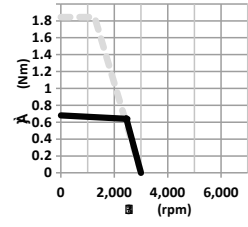
SM0601GE4(200 Watts) -10Amps
DC Bus--48VDC



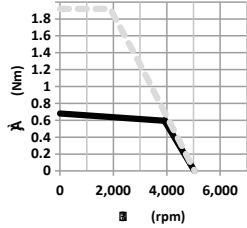
SM0601GE4(200 Watts) -10Amps
DC Bus--60VDC



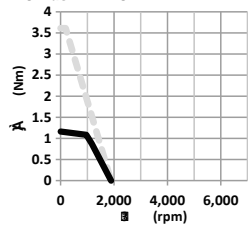
SM0601EE4(200 Watts) -5.2Amps
DC Bus--48VDC



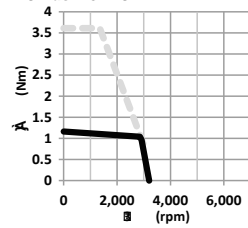
SM0601EE4(200 Watts) -5.2Amps
DC Bus--60VDC



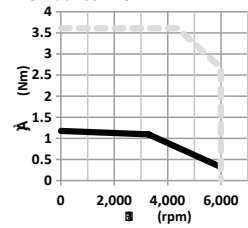
SM0602FE4(400 Watts) -10Amps
DC Bus--24VDC



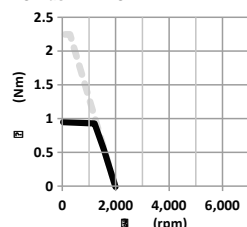
SM0602FE4(400 Watts) -10Amps
DC Bus--48VDC



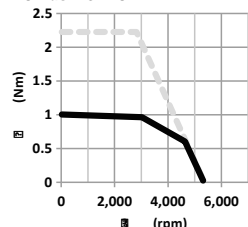
SM0602FE4(400 Watts) -10Amps
DC Bus--60VDC



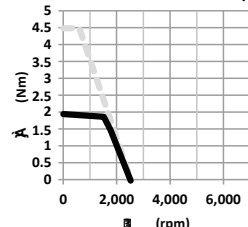
SM0801GE4(300 Watts) -10Amps
DC Bus--24VDC



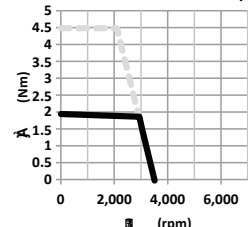
SM0801GE4(300 Watts) -10Amps
DC Bus--48VDC



SM0802 (550 Watts) - H7 E
48 VDC - 10 Amps



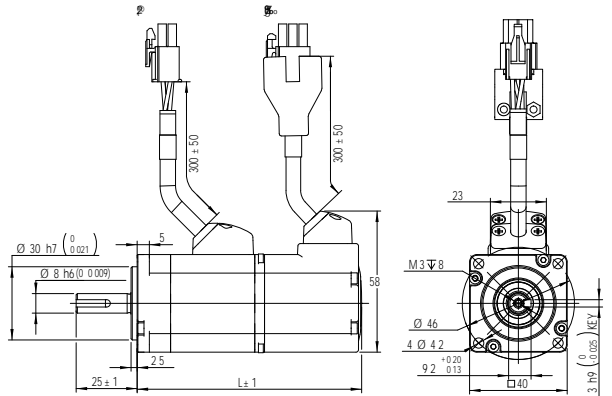
SM0802 (550 Watts) - H7 E
60VDC - 10 Amps



#7 n{A}
#7]A}

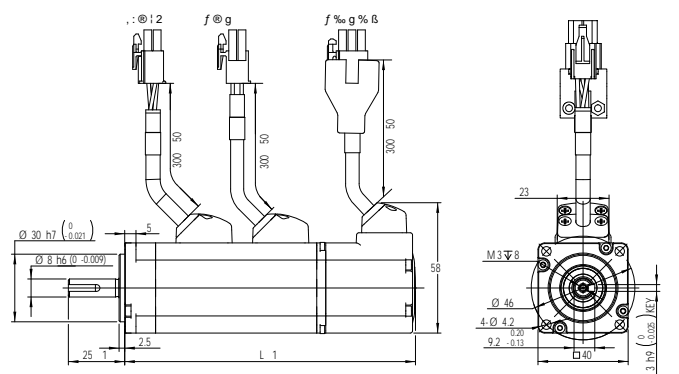
■ i(,,: Û F)(in : mm)

□ 40 i(,,: Æ f@g:Ë



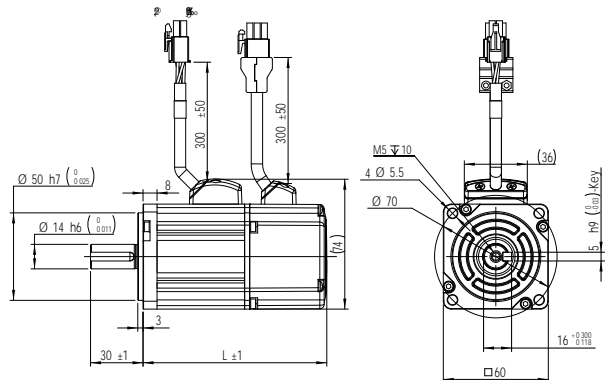
Æ f@g:Ë	L
SM0401EE4-KCD-NNV SM0401HE4-KCD-NNV	92
SM0402FE4-KCD-NNV	109

□ 40 i(,,: Û f@g:Ë



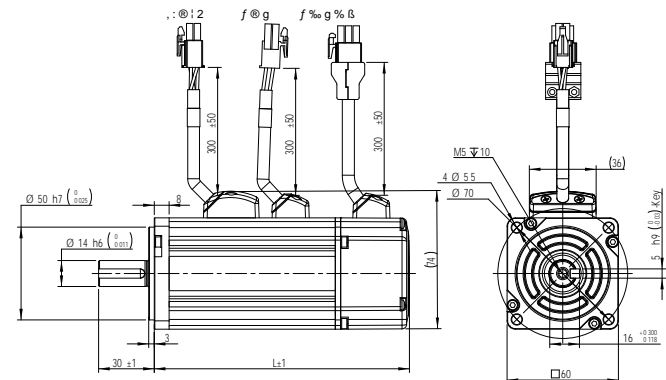
f@g:Ë	L
SM0401EE4-KCD-BNV SM0401HE4-KCD-BNV	129
SM0402HE4-KCD-BNV	147

□ 60 i(,,: Æ f@g:Ë



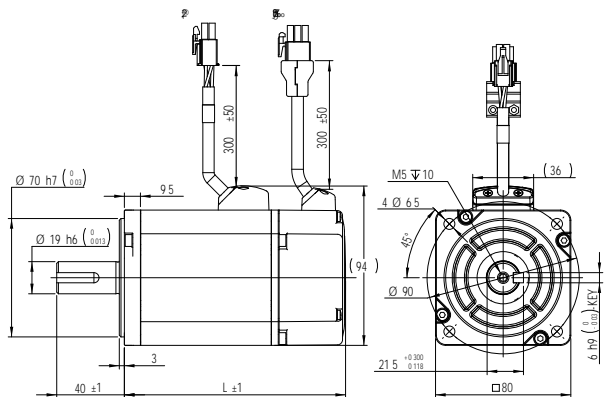
无制动器机型	L
SM0601GE4-KCF-NNV SM0601EE4-KCD-NNV	105
SM0602FE4-KCF-NNV	125

□ 60 i(,,: Û f@g:Ë



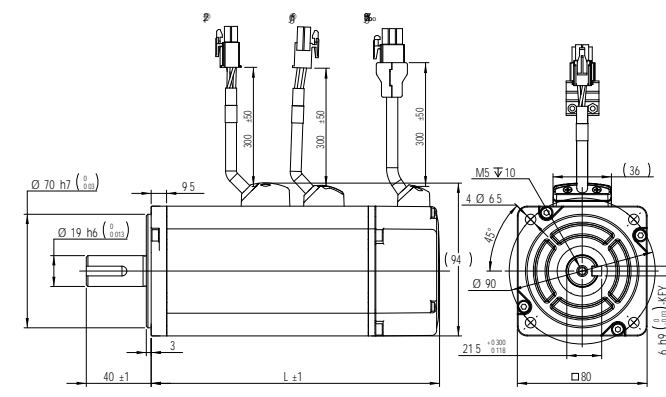
制动器机型	L
SM0601GE4-KCF-BNV SM0601EE4-KCD-BNV	145
SM0602FE4-KCF-BNV	165

□ 80 i(,,: Æ f@g:Ë



无制动器机型	L
SM0801GE4-KCF-NNV	101
SM0802EE4-KCF-NNV	116

□ 80 i(,,: Û f@g:Ë



制动器机型	L
SM0801GE4-KCF-BNV	148
SM0802EE4-KCF-BNV	163

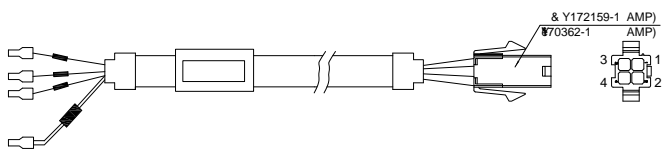
■ ,:®|2 — DC-6D0 x

□ / x 2

Ě A	
1630-100	DC-6D0 ,: 2/x Ě , 1 Ú
1630-300	DC-6D0 ,: 2/x Ě , 3 Ú
1630-500	DC-6D0 ,: 2/x Ě , 5 Ú
1630-1000	DC-6D0 ,: 2/x Ě , 10 Ú

□ €-,u — S Ā Ě

Ě A	
1631-100	DC-6D0 ,: 2 S Ā Ě , 1 Ú, Ů U
1631-300	DC-6D0 ,: 2 S Ā Ě , 3 Ú, Ů U
1631-500	DC-6D0 ,: 2 S Ā Ě , 5 Ú, Ů U
1631-1000	DC-6D0 ,: 2 S Ā Ě , 10 Ú, Ů U



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5452571 (Phoenix)			AMP 172159-1
-	U		1
-	V	æ	2
-	W	ī	3
Ā ě	PE	æ/ n	4

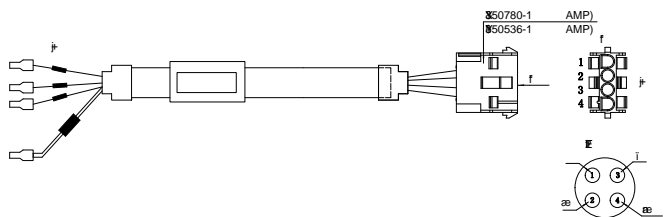
■ ,:®|2 — DC-10D x

□ / x 2

Ě A	
1627-100	DC-10D ,: 2/x Ě , 1 Ú, Ů U
1627-300	DC-10D ,: 2/x Ě , 3 Ú, Ů U
1627-500	DC-10D ,: 2/x Ě , 5 Ú, Ů U
1627-1000	DC-10D ,: 2/x Ě , 10 Ú, Ů U

□ €-,u — S Ā Ě

Ě A	
1628-100	DC-10D ,: 2 S Ā Ě , 1 Ú, Ů U
1628-300	DC-10D ,: 2 S Ā Ě , 3 Ú, Ů U
1628-500	DC-10D ,: 2 S Ā Ě , 5 Ú, Ů U
1628-1000	DC-10D ,: 2 S Ā Ě , 10 Ú, Ů U



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5452571 (Phoenix)			AMP 350780-1
-	U		1
-	V	æ	2
-	W	ī	3
Ā ě	PE	æ/ n	4

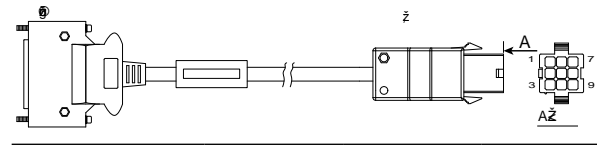
■ f%g 2

□ / x 2

Ě A	
2627-100	f%g 2/x Ě , 1 Ú, Ů U
2627-300	f%g 2/x Ě , 3 Ú, Ů U
2627-500	f%g 2/x Ě , 5 Ú, Ů U
2627-1000	f%g 2/x Ě , 10 Ú, Ů U

□ €-,u — S Ā Ě

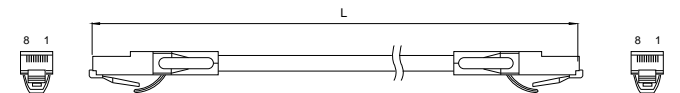
Ě A	
2621-100	f%g S Ā Ě 2, 1 Ú
2621-300	f%g S Ā Ě 2, 3 Ú
2621-500	f%g S Ā Ě 2, 5 Ú
2621-1000	f%g S Ā Ě 2, 10 Ú



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TYCO 3-2232346-1			AMP 172161-1
1	A+/U+	ī	1
2	B+/V+	n	2
3	Z+/W+	æ	3
14	A-/U-	ī / ě	4
15	B-/V-	n / ě	5
16	Z-/W-	æ/ ě	6
11	+5V		7
24	GND	ě	8
26	Shield	Shield	9

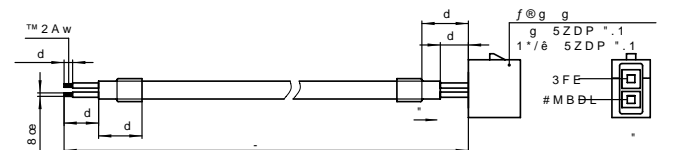
■ CN6\CN7 RS-485 / CANopen – V p X 2

Ě A	
2012-030	þ/\$P 2 , 0.3 Ú
2012-300	þ/\$P 2 , 3 Ú
2013-030	U \$P 2 , 0.3 Ú
2013-300	U \$P 2 , 3 Ú



■ ,:f@g"Á 2

Ě A	
1602-300	,:†»g"Á 2 , 3 Ú



■ i(, : g R G

Ē A	Motor Connector Kit
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□ . d 7 G

O %	Ē A	œ Û	f 4 ÷	
g (ò @ g ž)	3-2232346-1	1	TYCO	CN3 f % g g
g	172159-1	1		, : @ † 2 x
g	172233-1	1		, : † » 2 x
g PIN ê	170362-1	6		, : @ † 2 x
g	172161-1	1		f % g x
g PIN ê	770834-1	9		

■ CN3 f % g / * " g

Ē A	26P
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□ . d 7 G

O %	Ē A	œ Û	f 4 ÷	
g (ò @ g ž)	3-2232346-1	1	TYCO	CN3 f % g g

■ USB mini-B / l μ 2

O %	Ē A	œ Û	f 4 ÷	
USB mini-B / l μ 2	2620-150	1		CN1 ¼ n : À ò @ g / l μ 2

■ CN2 I/O / * " g

Ē A	50P
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□ . d 7 G

O %	Ē A	œ Û	f 4 ÷	
g (ò @ g ž)	5-2232346-1	1	TYCO	CN2 I/O g

■ STO © ^ g R G

Ē A	STO Connector Kit
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□ . d 7 G

O %	Ē A	œ Û	f 4 ÷	
STO € 2 7 G	STO € 2 7 G	1	Molex	ò @ g CN5 /
g	43025-1000	1		
g PIN ê	43030-0005	10		